



AN INPUT TO ACHIEVE

**FUNCTIONAL SAFETY**



# Safety first

**Leine & Linde – an important part in designing safe operations and safe machines.**

The best encoder solutions improve uptime, safety and performance. Leine & Linde encoders are known for their accuracy, enduring both harsh working conditions and long working hours.

Achieve functional safety in environments where temperature differences, dirt, shock, and vibrations are common. Meet some of the most robust rotary encoders on the market.



# The functional safety concept

To protect workers and to be able to sell a machine within the European market it is mandatory that the machine complies with the machinery directive, 2006/42/EC, and by that fulfills the part concerning functional safety. Functional safety is about reducing hazardous risks to maintain a safe machine for the operator.

## Performance level and safety integrity level

To show conformance to the machinery directive the machine manufacturer has to comply to a standard from the list of harmonized standards ([www.newapproach.org](http://www.newapproach.org)). Unlike the machinery directive, fulfillment of the standards is not legally mandated. However, if the harmonized standards are fulfilled, it is considered that all safety requirements of the machinery directive are as well.

The harmonized standards for showing compliance to the machinery directive, regarding functional safety, are either EN ISO 13849 or EN IEC 62061. EN ISO 13849 derives from EN 954-1 and is used for safety solutions where the safety is classified according to performance level PL a, b, c, d or e in ascending safety-related effectiveness. For functional safety of safety-related electrical, electronic and programmable electronic control systems, EN IEC 62061 is the choice. Note, in EN IEC 62061 the

functional safety system is composed of subsystems certified according to IEC 61508 which classifies the various safety categories in safety integrity levels (SIL 1, 2, 3 and 4). IEC 61508 also shows a probabilistic view of dangerous failures. Each of the various SIL levels describes a maximum permissible residual risk for a dangerous failure (PFH) of a machine or machine system.

The standards above are correlating to each other in some aspects; if low-complexity subsystems are designed according to EN IEC 62061 the standard refers to EN ISO 13849. It is similar for the performance level e within EN ISO 13849 which is referring to IEC 61508-3 because it covers safety-related embedded software for components with  $PL_r = e$ .

## Risk assessment and risk reduction

When designing a machine, it is mandatory for the machine builder to estimate how dangerous the machine will be, if a loss of the safety function occurs. This is done according to EN ISO 12100, by analyzing the risks and evaluating how to eliminate or minimize them. By performing the risk analysis a required risk reduction level is established (according to either PL or SIL) and this is the level of safety that the functional safety system has to fulfill in order to be considered as a human safe machine.

Furthermore the system has to be calculated based on the values of its containing components in order to meet the risk reduction level. It is within this calculation the reliability value of the encoder is needed.

## SIL2 or PLd

The Leine & Linde encoders are to be used as input components in a functional safety system. Therefore  $MTTF_d$  (EN ISO 13849) or  $PFH_d$  (IEC 61508) values are provided, for calculation of the safety in the system and thereby to make sure it meets the requirements of the risk reduction level. For most industrial applications where the encoders are used, SIL2/PLd is enough to meet the safety requirements. However it is possible to achieve different levels of risk reduction depending on the encoder input and the system architecture, from a minimum level of SIL1/PLc to a maximum level SIL3/PLe.

## Abbreviations

$MTTF_d$  = Mean time to dangerous failure [years]

PFH = Probability of a dangerous failure per hour [ $h^{-1}$ ]

SIL = Safety integrity level

PL = Performance level

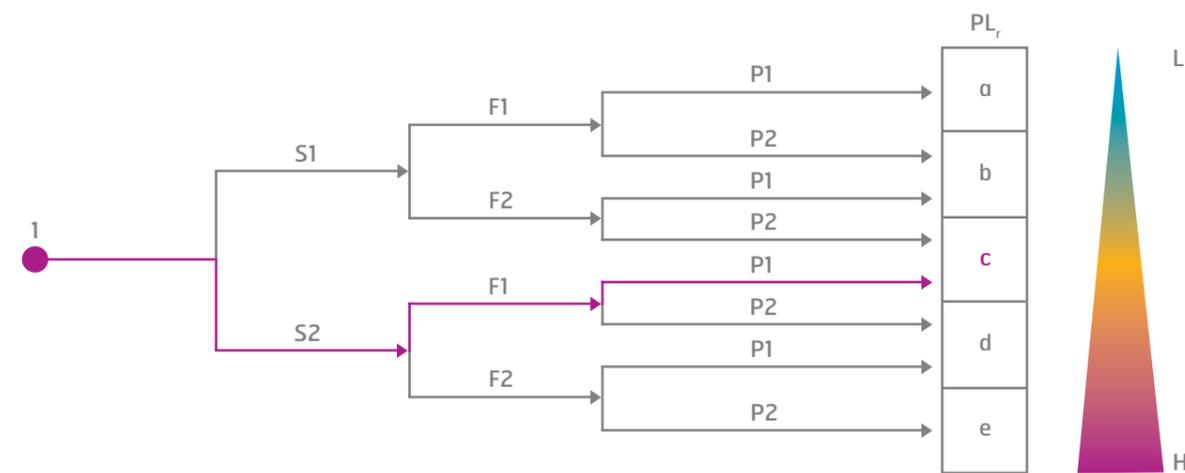


# Evaluation of performance level

The evaluation is required to make sure that the designed system has a performance level that is equivalent or higher than the required performance level  $c$  ( $PL_r=c$ ) on this page. This to be sure that the machine will be safe for the operator.

## Risk graph for determining required $PL_r$ according to EN ISO 13849-1

This graph contains the three factors that are used within the risk assessment to determine how high the risk of injury can get if loss of the safety function.



### Key

- 1 Starting point for evaluation of safety function's contribution to risk reduction.
- L Low contribution to risk reduction
- H High contribution to risk reduction
- $PL_r$  Required performance level

### Risk parameters

- S Severity of injury
- S1 Slight (normally reversible injury)
- S2 Serious (normally irreversible injury or death)
- F Frequency and/or exposure to hazard
- F1 Seldom-to-less-often and/or exposure time is short
- F2 Frequency-to-continuous and/or exposure time is long
- P Possibility of avoiding hazard or limiting harm
- P1 Possible under specific conditions
- P2 Scarcely possible

## Tables from EN ISO 13849-1 to establish the performance level

The relationship between  $MTTF_d$ , Diagnostic coverage (DC) and the category of the system results in the performance level of it.

| Denotation of each channel | $MTTF_d$   |
|----------------------------|--|
| Low                        | $3 \text{ years} \leq MTTF_d < 10 \text{ years}$   |
| Medium                     | $10 \text{ years} \leq MTTF_d < 30 \text{ years}$  |
| High                       | $30 \text{ years} \leq MTTF_d < 100 \text{ years}$ |

### Key

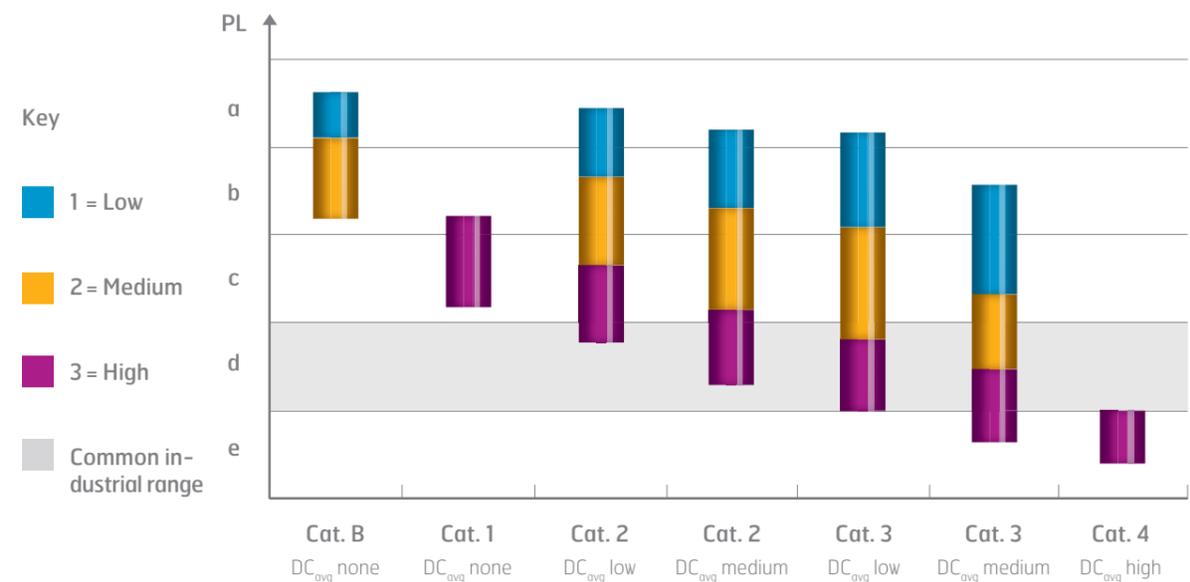
PL performance level

1  $MTTF_d$  of each channel = low

2  $MTTF_d$  of each channel = medium

3  $MTTF_d$  of each channel = high

| Denotation | Range                 |
|------------|-----------------------|
| None       | $DC < 60\%$           |
| Low        | $60\% \leq DC < 90\%$ |
| Medium     | $90\% \leq DC < 99\%$ |
| High       | $99\% \leq DC$        |



After finding out the required performance level for the application, use the examples on pages 8-9 to understand how the encoders meet the level in question. Depending on the design of the functional safety system, it is possible to achieve different performance levels.

# System solutions

Leine & Linde encoders are suitable for functional safety systems in all heavy duty applications. Depending on the system components as well as the system category, DC and MTTFd, different levels of risk reduction can be achieved.

## PLc achieved with system category 1 according to EN ISO 13849-1

For some applications it is enough using a single channel system due to either other combinations of safety equipments or due to the low hazardous risks. This safety system cuts the current supply to the motor to make sure a stop.



1. Encoder 1 Vpp, MTTFd > 100 years, DC\* = 99%
2. Logic MTTFd > 100 years, DC = 90%
3. Output MTTFd > 100 years, DC = 90%

\* The diagnostic coverage (DC) is based on the monitoring of the logic.

$$\frac{1}{\frac{1}{MTTF_{d\text{encoder}}} + \frac{1}{MTTF_{d\text{logic}}} + \frac{1}{MTTF_{d\text{output}}}} = MTTF_{d\text{system}} \text{ [years]}$$

This results in a MTTFd value > 100 years.

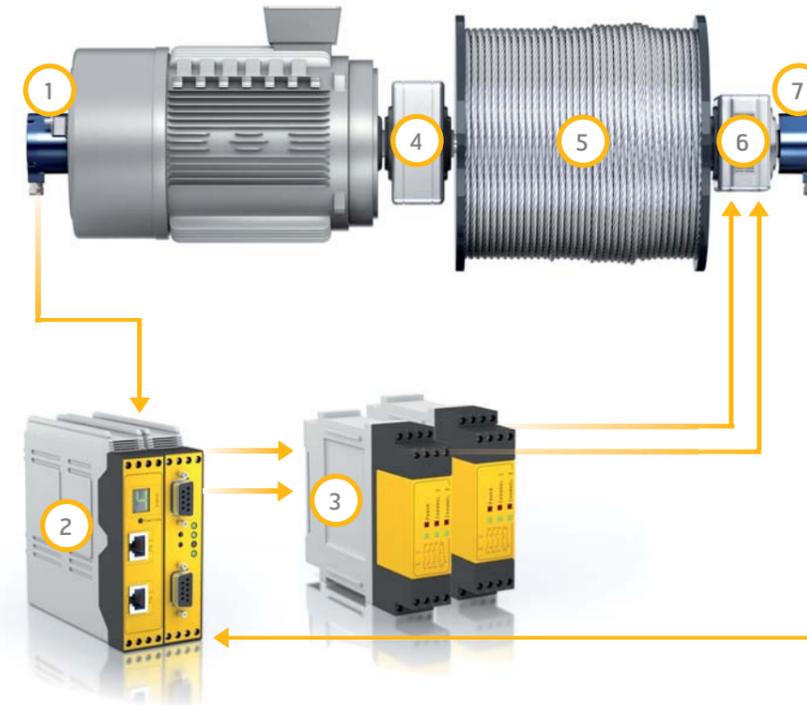
$$\frac{\frac{DC_{\text{encoder}}}{MTTF_{d\text{encoder}}} + \frac{DC_{\text{logic}}}{MTTF_{d\text{logic}}} + \frac{DC_{\text{output}}}{MTTF_{d\text{output}}}}{\frac{1}{MTTF_{d\text{encoder}}} + \frac{1}{MTTF_{d\text{logic}}} + \frac{1}{MTTF_{d\text{output}}}} = DC_{\text{avg system}} \text{ [%]}$$

This calculation results in a DCavg = 90,5%.

With these values the performance level of the system is established as PLc according to the table on page 7.

## PLd achieved with system category 3 according to EN ISO 13849-1

In this example the use of two encoders creates a two channel system for redundancy to ensure functioning of the safety function: to stop the drum if a hazardous situation occurs.



1. Encoder 1 Vpp, MTTFd > 100 years, DC\* = 99%
2. Logic MTTFd > 100 years, DC = 90%
3. Outputs MTTFd > 100 years, DC = 90%
4. Gearbox (Failures of the gearbox has to be considered when designing the system)
5. Drum
6. Brake B10d = 6 x 10<sup>6</sup> (Redundant according to category 3)
7. Encoder 1 Vpp, MTTFd > 100 years, DC\* = 99%

\* The diagnostic coverage (DC) is based on the monitoring of the logic.

$$\frac{1}{\frac{1}{MTTF_{d\text{encoder 1}}} + \frac{1}{MTTF_{d\text{logic}}} + \frac{1}{MTTF_{d\text{output}}} + \frac{1}{MTTF_{d\text{brake}}}} = MTTF_{d\text{channel 1}}$$

$$\frac{1}{\frac{1}{MTTF_{d\text{encoder 2}}} + \frac{1}{MTTF_{d\text{logic}}} + \frac{1}{MTTF_{d\text{output}}} + \frac{1}{MTTF_{d\text{brake}}}} = MTTF_{d\text{channel 2}}$$

$$\frac{2}{3} \left( MTTF_{d\text{ch 1}} + MTTF_{d\text{ch 2}} - \frac{1}{\frac{1}{MTTF_{d\text{ch 1}}} + \frac{1}{MTTF_{d\text{ch 2}}}} \right) = MTTF_{d\text{system}} \text{ [years]}$$

This results in a MTTFd value > 100 years.

$$\frac{\frac{DC_{\text{encoder 1}}}{MTTF_{d\text{encoder 1}}} + \frac{DC_{\text{encoder 2}}}{MTTF_{d\text{encoder 2}}} + \frac{DC_{\text{logic}}}{MTTF_{d\text{logic}}} + \left( 2x \frac{DC_{\text{output}}}{MTTF_{d\text{output}}} \right) + \left( 2x \frac{DC_{\text{brake}}}{MTTF_{d\text{brake}}} \right)}{\frac{1}{MTTF_{d\text{encoder 1}}} + \frac{1}{MTTF_{d\text{encoder 2}}} + \frac{1}{MTTF_{d\text{logic}}} + \left( 2x \frac{1}{MTTF_{d\text{output}}} \right) + \left( 2x \frac{1}{MTTF_{d\text{brake}}} \right)} = DC_{\text{avg system}} \text{ [%]}$$

This calculation results in a DCavg = 98,2%.

Please note that this are only brief examples and therefore not to be used as guidance. For more detailed information regarding the calculation, please refer to EN ISO 13849-1.

With these values the performance level of the system is established as PLd according to the table on page 7.

# Mechanical safety

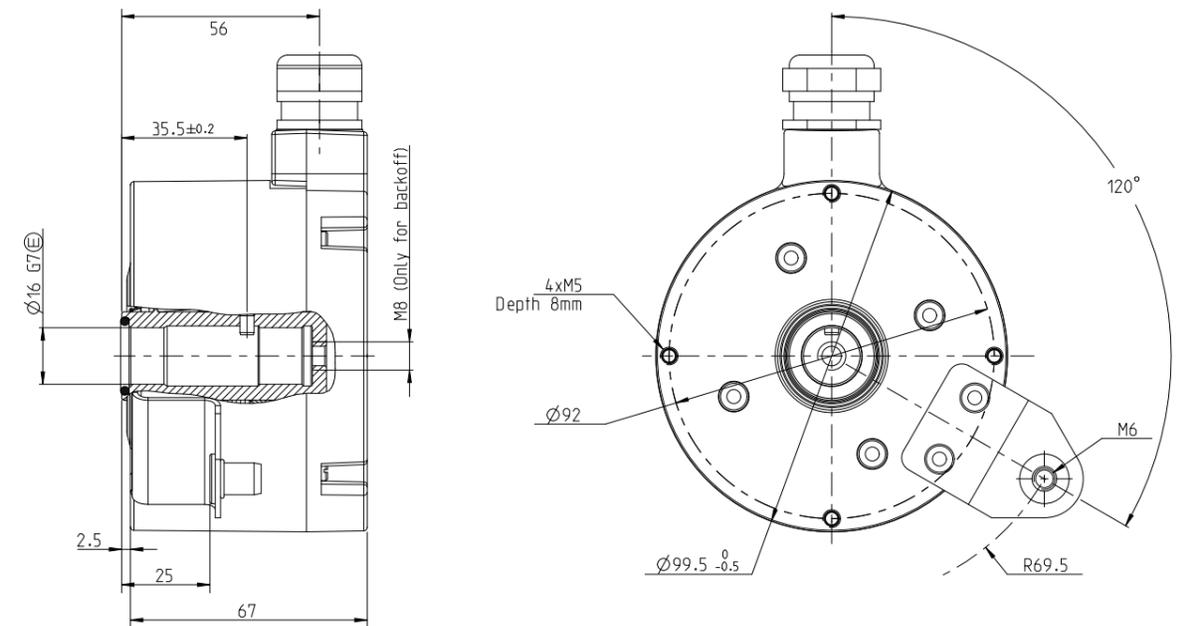
In addition to tightening screws slip-free mechanical adaption of shaft inlet is required to ensure a safe installation.

If a hollow shaft encoder is mounted to a solid round shaft, the risk of slipping is high and undetectable. To avoid this scenario Leine & Linde provides slip-free shaft solutions, such as the key in the 800 series hollow shaft encoder, which prevents the user to mount the encoder to a solid round adapter shaft.

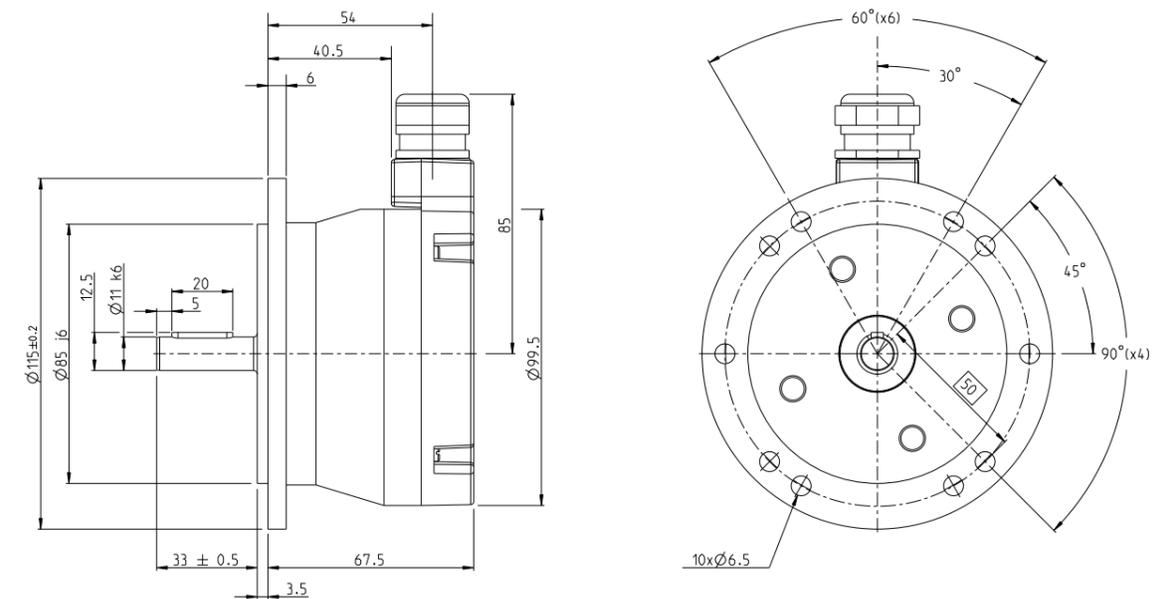
For the 500 and the 600 encoder series solid shaft with flat or key is available.



## Hollow shaft encoder with key



## Solid shaft encoder with key



For more information regarding solutions for mechanical safety, please contact Leine & Linde.

# Encoders for a safe system

This spread offers an overview of rotary encoders available with reliability values for functionally safe systems. There is also a solution where functional safety is integrated into the product: the Leine & Linde FSI series. Thanks to the series' SIL2/PLd certified safe functions, the machine directives are fulfilled just by using this solution correctly.

## The 800 series heavy duty encoder

Available with 1 Vpp for use in more demanding safety system where the required risk reduction is high.

|                         |   |
|-------------------------|---|
| Output signal           | 1 Vpp, TTL, HTL or HCHTL  |
| Encapsulation           | IP67 (IP66 at shaft inlet)  |
| Rotation speed max      | 6000 rpm  |
| Force (radial / axial)  | 300 N / 100 N   |
| Vibration               | ≤ 200 m/s <sup>2</sup>  |
| Shock                   | ≤ 1500 m/s <sup>2</sup>   |
| MTTF <sub>a</sub> value | 1 Vpp, 5 V: 770 years, terminal connection<br>HCHTL, 9-30 V: 421 years, terminal connection                                 |
| PFH value               | 1 Vpp, 5 V: 4,173E-7 h <sup>-1</sup> , terminal connection<br>HCHTL, 9-30 V: 7,425E-7 h <sup>-1</sup> , terminal connection |



## The 700 series compact encoder

In tight spaces where there is need for a robust encoder, the 700 series is the option.

|                         |   |
|-------------------------|---|
| Output signal           | 1 Vpp, HTL or HCHTL   |
| Encapsulation           | IP67 (IP66 at shaft inlet)  |
| Rotation speed max      | 6000 rpm  |
| Force (radial / axial)  | 50 N / 100 N  |
| Vibration               | ≤ 200 m/s <sup>2</sup>  |
| Shock                   | ≤ 1500 m/s <sup>2</sup>   |
| MTTF <sub>a</sub> value | 1 Vpp, 5 V: 483 years, connector or cable<br>HCHTL, 9-30 V: 224 years, connector or cable                 |
| PFH value               | 1 Vpp, 2,36E-7 h <sup>-1</sup> , connector or cable<br>HCHTL, 5,8E-7 h <sup>-1</sup> , connector or cable |



## The 600 series industrial encoder

The inductive 600 series absolute encoder with SSI interface has a 1 Vpp output signal for use within functional safety applications.

|                         |  |
|-------------------------|--|
| Output signal           | SSI, 1 Vpp, 32 ppr                               |
| Encapsulation           | IP67   |
| Rotation speed max      | 12000 rpm  |
| Force (radial / axial)  | 125 N / 100 N                                    |
| Vibration               | ≤ 300 m/s <sup>2</sup>                           |
| Shock                   | ≤ 2000 m/s <sup>2</sup>                          |
| MTTF <sub>a</sub> value | 1 Vpp, 9-30 V: 715 years, M23 connector          |
| PFH value               | 9-30 V: 3,555E-7 h <sup>-1</sup> , M23 connector |



## The 500 series robust encoder

When looking for a Ø58 mm encoder with unrivalled performance. With its HTL output the encoder can be used in environment where the cable distances are long and electronic signals are required.

|                         |  |
|-------------------------|--|
| Output signal           | HTL  |
| Encapsulation           | IP67 (IP66 at shaft inlet)                       |
| Rotation speed max      | 6000 rpm   |
| Force (radial / axial)  | 60 N / 50 N                                      |
| Vibration               | ≤ 300 m/s <sup>2</sup>                           |
| Shock                   | ≤ 2000 m/s <sup>2</sup>                          |
| MTTF <sub>a</sub> value | HTL, 6 channel, 9-30 V: 773 years                |
| PFH value               | HTL, 6 channel, 9-30 V: 5,853E-7 h <sup>-1</sup> |



## The FSI series – functional safety integrated

The FSI series is a functional safety product series provided by Leine & Linde. The series offers a great variety of functionalities, with absolute and incremental encoder signals, shaft and hollow-shaft mounting, as well as robust construction and encapsulation.

The encoder solutions are SIL2/PLd certified, including different safety functions such as overspeed, acceleration, end limits, and standstill. The FSI series monitors its own performance in a functionally safe manner, and thereby it can serve a functionally safe system with or without a functionally safe certified PLC.

Read more in the product brochure for the FSI series.



For more information about the encoder series please visit [www.leinelinde.com](http://www.leinelinde.com).

# Electronics

## Square waves

Square waves are the most common signal type for an incremental encoder. Leine & Linde's products are supplied as standard with 6 channels. Signal S00 is followed by signal S90, which is displaced 90 electrical degrees. The two inverted signals S00\ and S90\ enable differential transmission, which reduces the sensitivity of the signals to electrical interference. To check the position of the shaft, a reference pulse is produced once per revolution, Sref with its inverse Sref\.



There are several variations of electrical interface with different supply voltages and signal levels. When choosing an interface, it is necessary to take into account factors in the motor's operating environment. The exact properties of the interface is affected by frequency, cable length and temperature.

| Interface        | TTL                               | HTL  | HCHTL                               |
|------------------|-----------------------------------|--|-------------------------------------|
| Supply           | 5 Vdc                             | 9-30 Vdc                                   | 9-30 Vdc                            |
| Output signal    | 5 Vdc                             | 9-30 Vdc                                   | 9-30 Vdc                            |
| Suitable for     | Low frequencies over short cables | High frequencies over medium-length cables | Medium frequencies over long cables |
| Max cable length | 50 m at 50 kHz                    | 100 m at 100 kHz                           | 350 m at 100 kHz                    |
| Temperature      | -40 .. +100 °C                    | -40 .. +100 °C                             | -40 .. +85 °C                       |

## Sine waves

Sine waves are an alternative form of output signal. The analogue signal produces a unique amplitude for each position on the wave, allowing interpolation and very high resolutions. The interface I Vpp is often used in safety-critical applications where detection are required of extremely small movements.



For further information regarding our encoders and functional safety, please contact your nearest distributor or call Leine & Linde at +46-(0)152-265 00. The wide range of encoder variation is always available at [www.leinelinde.com](http://www.leinelinde.com).

# Contact us

## SWEDEN / HEAD OFFICE

T +46-(0)152-265 00  
F +46-(0)152-265 05  
info@leinelinde.com

## BRAZIL

T +55-19-3291 8425  
F +55-19-3367 5658  
info@leinelinde.com.br

## FINLAND

T +358-(0)9-561 72 00  
F +358-(0)9-561 72 020  
info@leinelinde.fi

## ITALY

T +39-039-596 01 08  
F +39-039-971 22 08  
info@leinelinde-ltn.it

## CHINA

T +86-(021)-525 835 66  
F +86-(021)-525 835 99  
info@leinelinde.cn

## GERMANY

T +49-(0)40-3176758-60  
F +49-(0)40-3176758-65  
info@leinelinde.de

## SOUTH KOREA

T +82-(0)51-746 54 20  
F +82-(0)51-746 54 21  
info@leinelinde.co.kr

## DENMARK

T +45-862-308 34  
info@leinelinde.dk

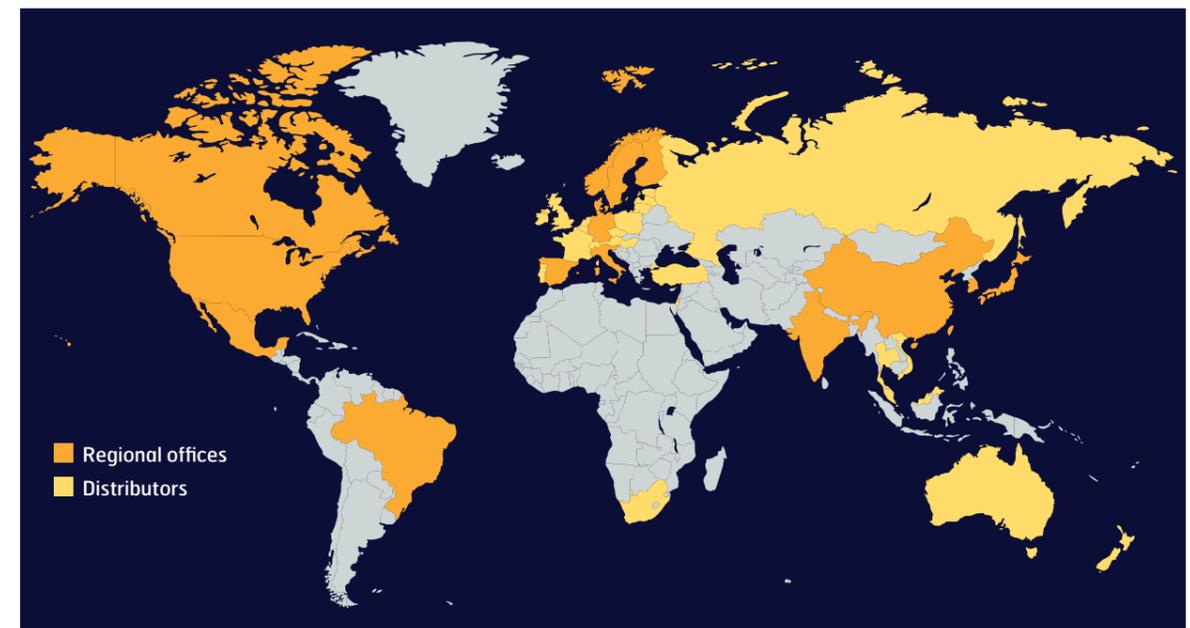
## INDIA

T +91-11-261 725 04  
F +91-11-261 654 49  
info@leinelinde.in

## SPAIN

T +34-93-574 23 02  
F +34-93-560 57 60  
info@leinelinde.es

Leine & Linde's worldwide presence. Read more at [www.leinelinde.com](http://www.leinelinde.com)





The best encoders are those you never have to think about. Those that simply do their job – year after year. Leine & Linde develops and manufactures customised encoder solutions for demanding environments, advanced measuring systems for accurate feedback of speed and position.

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+46-(0)152-265 00 [www.leinelinde.com](http://www.leinelinde.com)